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http://kubios.uef.fi

USER'S GUIDE

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Chapter 1

Overview

Kubios HRV is an advanced tool for studying the variability of heart beat intervals. Due to its wide variety of different analysis options and the easy to use interface, the software is suitable for researchers and clinicians with varying premises. The software is mainly designed for the analysis of normal human HRV, but can also be used e.g. for animal research.

Kubios HRV includes all the commonly used time- and frequency-domain variables of HRV. The frequency-domain variables are calculated for both nonparametric (Fourier transform based) and parametric (autoregressive modeling based) spectrum estimates. In addition, several nonlinear HRV variables are calculated such as Poincaré plot, recurrence plot analysis, detrended fluctuation analysis, approximate and sample entropies, and correlation dimension.

The Kubios HRV, heart rate variability (HRV) analysis software¹, is developed by the Biosignal Analysis and Medical Imaging Group (BSAMIG) at the Department of Applied Physics, University of Eastern Finland, Kuopio, Finland. The first version of the software was published already at the end of 2002 and is described in [33]. The current version is the third published version of the software. The versions published so far (including the current version) and a short description of their main features are listed below:

- Version 1.1 (released in September 2002): This was the first version of the Kubios HRV software which was distributed only for Windows operating systems. It included the basic HRV time-domain and frequency-domain analysis features. This version supported only ASCII RR interval data files as input.
- Version 2.0 (released in October 2008): The second version of the software was released for both Windows and Linux operating systems. The most significant new features in this version included Suunto SDF/STE and Polar HRM data file support, RR interval artifact correction options, several new nonlinear analysis features, and improved user interface.
- Version 2.1 (released in July 2012): The current version is released for Windows and Linux operating systems. The main new features compared to previous versions include ECG data support with integrated QRS detection algorithm, saving the analysis results in "SPSS friendly" ASCII file, and several usability related improvements.
- Version 2.2 (released in May 2014): The current version is released for Windows, Linux and Mac operating systems. New features compared to previous version include several improvements for input data support (support for Garmin FIT files and EDF+ annotations was added and Biopac file support updated), multiscale entropy (MSE) computation and several minor functionality and usability modifications.

The latest version of Kubios HRV has been developed using MATLAB® Release 2012a (The Math-Works, Inc.) and was compiled to a deployable standalone application with the MATLAB® Compiler 4.17. The MATLAB® Compiler Runtime (MCR) version 7.17 is required for running Kubios HRV and is included in the Kubios HRV installers.

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1.1 System requirements

The system requirements given below should be considered as recommended system requirements. The software may work also with lower system specifications, but will probably function slower or with reduced usability.

1.1.1 Windows

- Operating system: Microsoft® Windows 7 or later
- Memory: 512 MB of RAM (1024 MB or higher recommended)
- Disk space: about 500 MB
- Desktop resolution of 1024×768 or higher
- The MATLAB® Compiler Runtime 7.17 (32 bit version) installation

1.1.2 Linux

- Operating system: a Linux distribution with kernel 2.4.x or 2.6.x and glibc (glibc6) 2.3.4 and above.
- Memory: 512 MB of RAM (1024 MB or higher recommended)
- Desktop resolution of 1024×768 or higher
- Disk space: about 460 MB
- The MATLAB® Compiler Runtime 7.17 (included in the Kubios HRV installer)

1.1.3 Mac OS

- Operating system: Mac OS X
- Memory: 512 MB of RAM (1024 MB or higher recommended)
- Desktop resolution of 1024×768 or higher
- Disk space: about 460 MB
- The MATLAB® Compiler Runtime 7.17 installation

1.2 Installation

1.2.1 Windows

Make sure that you have administrative privileges (you will need them to install Kubios HRV). In order to install Kubios HRV on a Windows computer, you need to first install the MATLAB® Compiler Runtime (MCR, version 7.17) on your computer. You can find the MCR installer from Kubios HRV home page (http://kubios.uef.fi/). After you have installed the MCR, run the Kubios HRV installer file. Follow the instructions given in the setup wizard to complete installation. You can launch the Kubios HRV by selecting it from the created Start Menu folder or by clicking the Desktop icon (if created). Please note that the starting of Kubios HRV also starts the MATLAB® Compiler Runtime and may take some time especially with older computers.

1.2.2 Linux

Run the Kubios HRV installer by typing sh KubiosHRV-linux-2.2_x86.run in the terminal and follow the instructions given on screen. The Kubios HRV installer also includes the MATLAB® Compiler Runtime. NOTE: If you run the installer as root, Kubios HRV will be installed on your computer system wide for all users. If you want to install Kubios HRV only for yourself, run the installer as local user.



1.3. Uninstallation 6

1.2.3 Mac OS

Download the zip-file from Kubios HRV home page (http://kubios.uef.fi/), which includes the MATLAB® Compiler Runtime (MCR, version 7.17) and the Kubios HRV application bundle. First install the MCR on your computer (under the MCRinstaller folder, run InstallForMacOSX). After you have installed the MCR, move the Kubios HRV application bundle into Applications on your computer. Kubios HRVis then ready to be launched.

Note, that the zip-file includes also a Sample Data folder, which includes few sample files by which you can use to make test runs with Kubios HRVor to examine the structure of certain Kubios compatible file formats. The zip-file includes also a run_kubioshrv.sh script which you need to run if you are experiencing problems in opening Kubios HRV. This script will add the necessary entries of MCR into system path (see the readme file for its usage).

1.3 Uninstallation

1.3.1 Windows

The preferred and the most straightforward way of uninstalling Kubios HRV is to use the automated uninstaller. The uninstaller can be launched by selecting "Uninstall Kubios HRV" from the software's Start menu folder (the default Start menu folder is Kubios HRV). The software can also be uninstalled from the "Add or Remove Programs" under the Windows Control Panel. The uninstaller does not remove your preferences settings. These have to be deleted manually from C:\Users\\appData\Roaming\KubiosHRV.

1.3.2 Linux

Open terminal and change directory to the Kubios HRV install directory. Run the command sh uninstall_kubios.sh and follow instructions given on screen. NOTE: You may need root privileges for running the uninstaller if you have installed Kubios HRV as root.

1.3.3 Mac OS

Move the installed applications (the MCR and Kubios HRV application) to trash.

1.4 Software home page

The Kubios HRV home page on the web can be found at

http://kubios.uef.fi/

where you can find current information on the software and download possible updates and related material. If you have any trouble or questions regarding the software, please check first if your particular problem or question has an answer in the FAQ/troubleshooting section at the software homepage!

1.5 Structure of this guide

The aim of this guide is to help the user to get started with Kubios HRV. It should not, however, be thought of as being an easy to follow step by step manual, but more like a reference material from which you can probably find answers to your problems related to HRV analysis or usability of the software. The structure of this guide is as follows.

After the overview chapter, from where you will find useful information about the system requirements and installation, an introduction to heart rate variability is given in Chapter 2. This chapter starts with a short discussion on the control systems of heart rate after which the extraction of heart beat periods is discussed and the derivation of HRV time series is described. The rest of the chapter is focused on the preprocessing of HRV data and gives a detailed description of the smoothness priors based detrending approach.

In Chapter 3, the analysis methods included in the software are described. The descriptions of the methods are divided into time-domain, frequency-domain and nonlinear categories and a summary of the methods is given at the end of the chapter. For most of the methods, exact formulas for the different variables are given and possible parameter selections are pointed out.

In Chapter 4, the description of the features and usage of the software is given. First, the input data formats supported by the software are described and then the user interface through which the software is operated is described. Then, different options for saving the analysis results are described and, finally, instructions on how to set up the preference values for the analysis options are given. So if you want to learn how to use all the functionalities of the software, this is the chapter to read!

In Chapter 5, two sample runs of the software are presented. The first sample run describes how to analyze the lying and standing periods of the orthostatic test measurement (distributed along this software) separately as stationary segments.

Chapter 2

Heart rate variability

Heart rate variability (HRV) describes the variations between consecutive heartbeats. The rhythm of the heart is controlled by the sinoatrial (SA) node, which is modulated by both the sympathetic and parasympathetic branches of the autonomic nervous system. Sympathetic activity tends to increase heart rate (HR \uparrow) and its response is slow (few seconds) [3]. Parasympathetic activity, on the other hand, tends to decrease heart rate (HR \downarrow) and mediates faster (0.2–0.6 seconds) [3]. In addition to central control, there are some feedback mechanisms that can provide quick reflexes. One such mechanism is the arterial baroreflex. This reflex is based on baroreceptors which are located on the walls of some large vessels and can sense the stretching of vessel walls caused by pressure increase. Both sympathetic and parasympathetic activity are influenced by baroreceptor stimulation trough a specific baroreflex arc, Fig. 2.1.

The continuous modulation of the sympathetic and parasympathetic innervations results in variations in heart rate. The most conspicuous periodic component of HRV is the so-called respiratory sinus arrhythmia (RSA) which is considered to range from 0.15 to 0.4 Hz [3]. In addition to the physiological influence of breathing on HRV, this high frequency (HF) component is generally believed to be of parasympathetic origin. Another widely studied component of HRV is the low frequency (LF) component usually ranging from 0.04 to 0.15 Hz including the component referred to as the 10-second rhythm or the Mayer wave [3]. The rhythms within the LF band have been thought to be of both sympathetic and parasympathetic origin [3] even though some researchers have suggested them to be mainly of sympathetic origin [26]. The fluctuations below 0.04 Hz, on the other hand, have not been studied as much as the higher frequencies. These frequencies are commonly divided into very low frequency (VLF, 0.003-0.04 Hz) and ultra low frequency (ULF, 0-0.003 Hz) bands, but in case of short-term recordings the ULF band is generally omitted [44]. These lowest frequency rhythms are characteristic for HRV signals and have been related to, e.g., humoral factors such as the thermoregulatory processes and renin-angiotensin system [3].

Even though HRV has been studied extensively during the last decades within which numerous research articles have been published, the practical use of HRV have reached general consensus only in two clinical applications [44]. That is, it can be used as a predictor of risk after myocardial infarction [25, 20] and as an early warning sign of diabetic neuropathy [5, 34]. In addition, HRV has been found to correlate with, e.g., age, mental and physical stress, and attention, see, e.g., the review in [3].

The term HRV refers, in general, to changes in heart beat interval which is a reciprocal of the heart rate. This is also the case here. The starting point for HRV analysis is the ECG recording from which the HRV time series can be extracted. In the formulation of the HRV time series, a fundamental issue is the determination of heart beat period.

2.1 Heart beat period and QRS detection

The aim in HRV analysis is to examine the sinus rhythm modulated by the autonomic nervous system. Therefore, one should technically detect the occurrence times of the SA-node action potentials. This is, however, practically impossible and, thus, the fiducial points for the heart beat is usually determined from the ECG recording. The nearest observable activity in the ECG compared to SA-node firing is the P-wave resulting from atrial depolarization (see Fig. 2.2) and, thus, the heart beat period is generally defined as the time difference between two successive P-waves. The signal-to-noise ratio of the P-wave is, however, clearly lower than that of the strong QRS complex which results primarily from ventricular depolarization. Therefore, the heart beat period is commonly evaluated as the time difference between

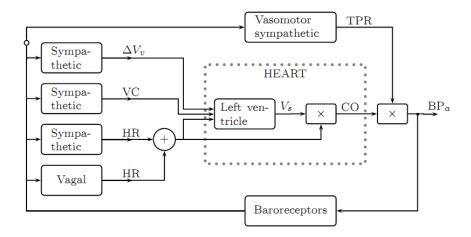


Figure 2.1: The four baroreflex pathways (redrawn from [42]). Variation in venous volume (ΔV_v), left ventricular contractility (VC), sympathetic and parasympathetic (vagal) control of heart rate (HR), stroke volume (V_s), cardiac output (CO), total peripheral resistance (TPR), and arterial blood pressure (BP_a).

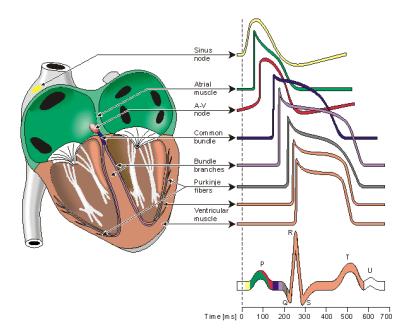


Figure 2.2: Electrophysiology of the heart (redrawn from [27]). The different waveforms for each of the specialized cells found in the heart are shown. The latency shown approximates that normally found in the healthy heart.

the easily detectable QRS complexes.

A typical QRS detector consists of a preprocessing part followed by a decision rule. Several different QRS detectors have been proposed within last decades [45, 35, 36, 18, 13]. For an easy to read review of these methods, see [1]. The preprocessing of the ECG usually includes at least bandpass filtering to reduce power line noise, baseline wander, muscle noise, and other interference components. The passband can be set to approximately 5–30 Hz which covers most of the frequency content of QRS complex [35]. In addition, preprocessing can include differentiation and/or squaring of the samples. After preprocessing, the decision rules are applied to determine whether or not a QRS complex has occurred. The decision rule usually includes an amplitude threshold which is adjusted adaptively as the detection progresses. In addition, the average heart beat period is often used in the decision. The fiducial point is generally selected to be the R-wave and the corresponding time instants are given as the output of the detector.

The accuracy of the R-wave occurrence time estimates is often required to be 1–2 ms and, thus, the sampling frequency of the ECG should be at least 500–1000 Hz [44]. If the sampling frequency of the

ECG is less than 500 Hz, the errors in R-wave occurrence times can cause critical distortion to HRV analysis results, especially to spectrum estimates [31]. The distortion of the spectrum is even bigger if the overall variability in heart rate is small [39]. The estimation accuracy can however be improved by interpolating the QRS complex e.g. by using a cubic spline interpolation [10] or some model based approach [4]. It should be, however, noted that when the SA-node impulses are of interest there is an unavoidable estimation error of approximately 3 ms due to fluctuations in the AV-nodal conduction time [42].

2.2 Derivation of HRV time series

After the QRS complex occurrence times have been estimated, the HRV time series can be derived. The inter-beat intervals or RR intervals are obtained as differences between successive R-wave occurrence times. That is, the n'th RR interval is obtained as the difference between the R-wave occurrence times $RR_n = t_n - t_{n-1}$. In some context, normal-to-normal (NN) may also be used when referring to these intervals indicating strictly intervals between successive QRS complexes resulting from SA-node depolarization [44]. In practice, the NN and RR intervals appear to be the same and, thus, the term RR is preferred here.

The time series constructed from all available RR intervals is, clearly, not equidistantly sampled, but has to be presented as a function of time, i.e. as values (t_n, RR_n) . This fact has to be taken into account before frequency-domain analysis. In general, three different approaches have been used to get around this issue [44]. The simplest approach that have been adopted in, e.g., [2] is to assume equidistant sampling and calculate the spectrum directly from the RR interval tachogram (RR intervals as a function of beat number), see the left panel of Fig. 2.3. This assumption can, however, cause distortion into the spectrum [29]. This distortion becomes substantial when the variability is large in comparison with the mean level. Furthermore, the spectrum can not be considered to be a function of frequency but rather of cycles per beat [11]. Another common approach, adopted in this software, is to use interpolation methods for converting the non-equidistantly sampled RR interval time series (also called the interval function) to equidistantly sampled [44], see the right panel of Fig. 2.3. One choice for the interpolation method is the cubic spline interpolation [29]. After interpolation, regular spectrum estimation methods can be applied. The third general approach called the spectrum of counts considers a series of impulses (delta functions positioned at beat occurrence times) [12]. This approach relies on the generally accepted integral pulse frequency modulator (IPFM) which aims to model the neural modulation of the SA-node [42]. According to this model, the modulating signal is integrated until a reference level is achieved after which an impulse is emitted and the integrator is set to zero. The spectrum of the series of events can be calculated, e.g., by first lowpass filtering the event series and then calculating the spectrum of the resulting signal [11].

2.3 Preprocessing of HRV time series

Any artifact in the RR interval time series may interfere the analysis of these signals. The artifacts within HRV signals can be divided into technical and physiological artifacts. The technical artifacts can include missing or additional QRS complex detections and errors in R-wave occurrence times. These artifacts may be due to measurement artifacts or the computational algorithm. The physiological artifacts, on the other hand, include ectopic beats and arrhythmic events. In order to avoid the interference of such artifacts, the ECG recording and the corresponding event series should always be manually checked for artifacts and only artifact-free sections should be included in the analysis [44]. Alternatively, if the amount of artifact-free data is insufficient, proper interpolation methods can be used to reduce these artifacts, see, e.g., [22, 23, 30].

Another common feature that can alter the analysis significantly are the slow linear or more complex trends within the analyzed time series. Such slow nonstationarities are characteristic for HRV signals and should be considered before the analysis. The origins of nonstationarities in HRV are discussed, e.g., in [3]. Two kinds of methods have been used to get around the nonstationarity problem. In [48], it was suggested that HRV data should be systematically tested for nonstationarities and that only stationary segments should be analyzed. Representativeness of these segments in comparison with the whole HRV signal was, however, questioned in [16]. Other methods try to remove the slow nonstationary trends from the HRV signal before analysis. The detrending is usually based on first order [24, 32] or higher order polynomial [40, 32] models. In addition, this software includes an advanced detrending procedure originally presented in [43]. This approach is based on smoothness priors regularization.



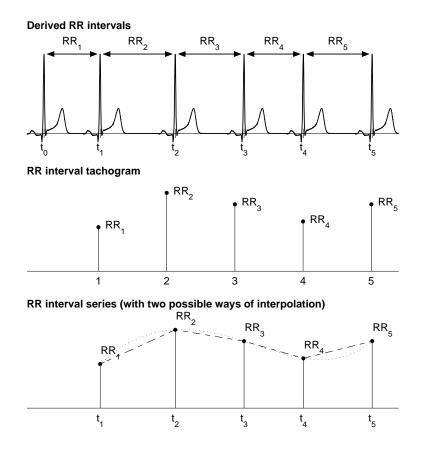


Figure 2.3: Derivation of two HRV signals from ECG: the interval tachogram (middle panel) and interpolated RR interval series (bottom panel).

2.3.1 Smoothness priors based detrending approach

Let $z \in \mathbb{R}^N$ denote the RR interval time series which can be considered to consist of two components

$$z = z_{\text{stat}} + z_{\text{trend}} \tag{2.1}$$

where $z_{\rm stat}$ is the nearly stationary RR interval series of interest, $z_{\rm trend}$ is the low frequency aperiodic trend component, and N is the number of RR intervals. Suppose that the trend component can be modeled with a linear observation model as

$$z_{\text{trend}} = H\theta + e \tag{2.2}$$

where $H \in \mathbb{R}^{N \times p}$ is the observation matrix, $\theta \in \mathbb{R}^p$ are the regression parameters, and e is the observation error. The task is then to estimate the parameters by some fitting procedure so that $\hat{z}_{\text{trend}} = H\hat{\theta}$ can be used as the estimate of the trend. The properties of the estimate depend strongly on the properties of the basis vectors (columns of the matrix H) in the fitting. A widely used method for the solution of the estimate $\hat{\theta}$ is the least squares method. However, a more general approach for the estimation of $\hat{\theta}$ is used here. That is, the so-called regularized least squares solution

$$\hat{\theta}_{\lambda} = \arg\min_{\theta} \left\{ \|z - H\theta\|^2 + \lambda^2 \|D_d(H\theta)\|^2 \right\}$$
(2.3)

where λ is the regularization parameter and D_d indicates the discrete approximation of the d'th derivative operator. This is clearly a modification of the ordinary least squares solution to the direction in which the side norm $||D_d(H\theta)||$ gets smaller. In this way, prior information about the predicted trend $H\theta$ can be implemented to the estimation. The solution of (2.3) can be written in the form

$$\hat{\theta}_{\lambda} = (H^T H + \lambda^2 H^T D_d^T D_d H)^{-1} H^T z \tag{2.4}$$

and the estimate for the trend which is to be removed as

$$\hat{z}_{\text{trend}} = H\hat{\theta}_{\lambda}. \tag{2.5}$$

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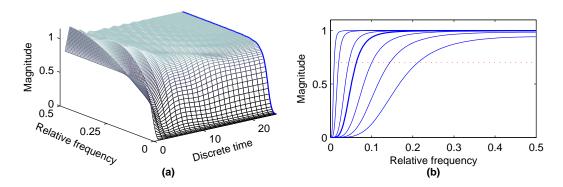


Figure 2.4: a) Time-varying frequency response of \mathcal{L} (N-1=50 and $\lambda=10$). Only the first half of the frequency response is presented, since the other half is identical. b) Frequency responses, obtained from the middle row of \mathcal{L} (cf. bold lines), for $\lambda=1,\,2,\,4,\,10,\,20,\,100$, and 500. The corresponding cut-off frequencies are 0.213, 0.145, 0.101, 0.063, 0.045, 0.021 and 0.010 times the sampling frequency.

The selection of the observation matrix H can be implemented according to some known properties of the data z. For example, a generic set of Gaussian shaped functions or sigmoids can be used. Here, however, the trivial choice of identity matrix $H = I \in \mathbb{R}^{N \times N}$ is used. In this case, the regularization part of (2.3) can be understood to draw the solution towards the null space of the regularization matrix D_d . The null space of the second order difference matrix contains all first order curves and, thus, D_2 is a good choice for estimating the aperiodic trend of RR series. With these specific choices, the detrended nearly stationary RR series can be written as

$$\hat{z}_{\text{stat}} = z - H\hat{\theta}_{\lambda} = (I - (I + \lambda^2 D_2^T D_2)^{-1})z.$$
(2.6)

In order to demonstrate the properties of the proposed detrending method, its frequency response is considered. Equation (2.5) can be written as $\hat{z}_{\text{stat}} = \mathcal{L}z$, where $\mathcal{L} = I - (I + \lambda^2 D_2^T D_2)^{-1}$ corresponds to a time-varying finite impulse response highpass filter. The frequency response of \mathcal{L} for each discrete time point, obtained as a Fourier transform of its rows, is presented in Fig. 2.4 (a). It can be seen that the filter is mostly constant but the beginning and end of the signal are handled differently. The filtering effect is attenuated for the first and last elements of z and, thus, the distortion of end points of data is avoided. The effect of the smoothing parameter λ on the frequency response of the filter is presented in Fig. 2.4 (b). The cutoff frequency of the filter decreases when λ is increased. Besides the λ parameter the frequency response naturally depends on the sampling rate of signal z.

Chapter 3

Analysis methods

In this chapter, the analysis methods used in the software are introduced. The presented methods are mainly based on the guidelines given in [44]. The presentation of the methods is divided into three categories, i.e. time-domain, frequency-domain and nonlinear methods. The methods summarized in Table 3.1.

3.1 Time-domain methods

The time-domain methods are the simplest to perform since they are applied straight to the series of successive RR interval values. The most evident such measure is the mean value of RR intervals (\overline{RR}) or, correspondingly, the mean HR (\overline{HR}) . In addition, several variables that measure the variability within the RR series exist. The standard deviation of RR intervals (SDNN) is defined as

$$SDNN = \sqrt{\frac{1}{N-1} \sum_{j=1}^{N} (RR_j - \overline{RR})^2}$$
(3.1)

where RR_j denotes the value of j'th RR interval and N is the total number of successive intervals. The SDNN reflects the overall (both short-term and long-term) variation within the RR interval series, whereas the standard deviation of successive RR interval differences (SDSD) given by

$$SDSD = \sqrt{E\{\Delta RR_j^2\} - E\{\Delta RR_j\}^2}$$
(3.2)

can be used as a measure of the short-term variability. For stationary RR series $E\{\Delta RR_j\} = E\{RR_{j+1}\} - E\{RR_j\} = 0$ and SDSD equals the root mean square of successive differences (RMSSD) given by

RMSSD =
$$\sqrt{\frac{1}{N-1} \sum_{j=1}^{N-1} (RR_{j+1} - RR_j)^2}$$
. (3.3)

Another measure calculated from successive RR interval differences is the NN50 which is the number of successive intervals differing more than 50 ms or the corresponding relative amount

$$pNN50 = \frac{NN50}{N-1} \times 100\%. \tag{3.4}$$

In addition to the above statistical measures, there are some geometric measures that are calculated from the RR interval histogram. The HRV triangular index is obtained as the integral of the histogram (i.e. total number of RR intervals) divided by the height of the histogram which depends on the selected bin width. In order to obtain comparable results, a bin width of 1/128 seconds is recommended [44]. Another geometric measure is the TINN which is the baseline width of the RR histogram evaluated through triangular interpolation, see [44] for details.

3.2 Frequency-domain methods

In the frequency-domain methods, a power spectrum density (PSD) estimate is calculated for the RR interval series. The regular PSD estimators implicitly assume equidistant sampling and, thus, the RR

interval series is converted to equidistantly sampled series by interpolation methods prior to PSD estimation. In the software a cubic spline interpolation method is used. In HRV analysis, the PSD estimation is generally carried out using either FFT based methods or parametric AR modeling based methods. For details on these methods see, e.g., [28]. The advantage of FFT based methods is the simplicity of implementation, while the AR spectrum yields improved resolution especially for short samples. Another property of AR spectrum that has made it popular in HRV analysis is that it can be factorized into separate spectral components. The disadvantages of the AR spectrum are the complexity of model order selection and the contingency of negative components in the spectral factorization. Nevertheless, it may be advantageous to calculate the spectrum with both methods to have comparable results.

In this software, the HRV spectrum is calculated with FFT based Welch's periodogram method and with the AR method. Spectrum factorization in AR method is optional. In the Welch's periodogram method the HRV sample is divided into overlapping segments. The spectrum is then obtained by averaging the spectra of these segments. This method decreases the variance of the FFT spectrum.

The generalized frequency bands in case of short-term HRV recordings are the very low frequency (VLF, 0–0.04 Hz), low frequency (LF, 0.04–0.15 Hz), and high frequency (HF, 0.15–0.4 Hz). The frequency-domain measures extracted from the PSD estimate for each frequency band include absolute and relative powers of VLF, LF, and HF bands, LF and HF band powers in normalized units, the LF/HF power ratio, and peak frequencies for each band (see Table 3.1). In the case of FFT spectrum, absolute power values for each frequency band are obtained by simply integrating the spectrum over the band limits. In the case of AR spectrum, on the other hand, if factorization is enabled distinct spectral components emerge for each frequency band with a proper selection of the model order and the absolute power values are obtained directly as the powers of these components. If factorization is disabled the AR spectrum powers are calculated as for the FFT spectrum. The band powers in relative and normalized units are obtained from the absolute values as described in Table 3.1.

3.3 Nonlinear methods

Considering the complex control systems of the heart it is reasonable to assume that nonlinear mechanisms are involved in the genesis of HRV. The nonlinear properties of HRV have been analyzed using measures such as Poincaré plot [6, 7], approximate and sample entropy [41, 14], detrended fluctuation analysis [37, 38], correlation dimension [17, 19], and recurrence plots [47, 46, 49]. During the last years, the number of studies utilizing such methods have increased substantially. The downside of these methods is still, however, the difficulty of physiological interpretation of the results.

3.3.1 Poincaré plot

One commonly used nonlinear method that is simple to interpret is the so-called Poincaré plot. It is a graphical representation of the correlation between successive RR intervals, i.e. plot of RR_{j+1} as a function of RR_j as described in Fig. 3.1. The shape of the plot is the essential feature. A common approach to parameterize the shape is to fit an ellipse to the plot as shown in Fig. 3.1. The ellipse is oriented according to the line-of-identity ($RR_j = RR_{j+1}$) [6]. The standard deviation of the points perpendicular to the line-of-identity denoted by SD1 describes short-term variability which is mainly caused by RSA. It can be shown that SD1 is related to the time-domain measure SDSD according to [6]

$$SD1^2 = \frac{1}{2}SDSD^2. \tag{3.5}$$

The standard deviation along the line-of-identity denoted by SD2, on the other hand, describes long-term variability and has been shown to be related to time-domain measures SDNN and SDSD by [6]

$$SD2^2 = 2 SDNN^2 - \frac{1}{2} SDSD^2.$$
 (3.6)

The standard Poincaré plot can be considered to be of the first order. The second order plot would be a three dimensional plot of values $(RR_j, RR_{j+1}, RR_{j+2})$. In addition, the lag can be bigger than 1, e.g., the plot (RR_j, RR_{j+2}) .

3.3.2 Approximate entropy

Approximate entropy (ApEn) measures the complexity or irregularity of the signal [14, 41]. Large values of ApEn indicate high irregularity and smaller values of ApEn more regular signal. The ApEn is computed



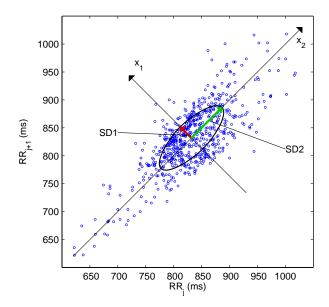


Figure 3.1: Poincaré plot analysis with the ellipse fitting procedure. SD1 and SD2 are the standard deviations in the directions x_1 and x_2 , where x_2 is the line-of-identity for which $RR_j = RR_{j+1}$.

as follows.

First, a set of length m vectors u_i is formed

$$u_j = (RR_j, RR_{j+1}, \dots, RR_{j+m-1}), \quad j = 1, 2, \dots N - m + 1$$
 (3.7)

where m is called the embedding dimension and N is the number of measured RR intervals. The distance between these vectors is defined as the maximum absolute difference between the corresponding elements, i.e.,

$$d(u_j, u_k) = \max \{ |RR_{j+n} - RR_{k+n}| \mid n = 0, \dots, m-1 \}.$$
(3.8)

Next, for each u_j the relative number of vectors u_k for which $d(u_j, u_k) \leq r$ is calculated. This index is denoted with $C_j^m(r)$ and can be written in the form

$$C_j^m(r) = \frac{\text{nbr of } \{u_k \mid d(u_j, u_k) \le r\}}{N - m + 1} \quad \forall k.$$
 (3.9)

Due to the normalization, the value of $C_j^m(r)$ is always smaller or equal to 1. Note that the value is, however, at least 1/(N-m+1) since u_j is also included in the count. Then, take the natural logarithm of each $C_j^m(r)$ and average over j to yield

$$\Phi^{m}(r) = \frac{1}{N - m + 1} \sum_{j=1}^{N - m + 1} \ln C_{j}^{m}(r).$$
(3.10)

Finally, the approximate entropy is obtained as

$$ApEn(m, r, N) = \Phi^{m}(r) - \Phi^{m+1}(r).$$
(3.11)

Thus, the value of the estimate ApEn depends on three parameters, the length m of the vectors u_j , the tolerance value r, and the data length N. In this software the default value of m is set to be m=2. The length N of the data also affects ApEn. When N is increased the ApEn approaches its asymptotic value. The tolerance r has a strong effect on ApEn and it should be selected as a fraction of the standard deviation of the data (SDNN). This selection enables the comparison of different data types. A common selection for r is r=0.2SDNN, which is also the default value in this software.

3.3.3 Sample entropy

Sample entropy (SampEn) is similar to ApEn, but there are two important differences in its calculation [41, 21]. For ApEn, in the calculation of the number of vectors u_k for which $d(u_i, u_k) \leq r$ also the



vector u_j itself is included. This ensures that $C_j^m(r)$ is always larger than 0 and the logarithm can be applied, but at the same time it makes ApEn to be biased. In sample entropy the self-comparison of u_j is eliminated by calculating $C_j^m(r)$ as

$$C_j^m(r) = \frac{\text{nbr of } \left\{ u_k \mid d(u_j, u_k) \le r \right\}}{N - m} \quad \forall k \ne j.$$
(3.12)

Now the value of $C_i^m(r)$ will be between 0 and 1. Next, the values of $C_i^m(r)$ are averaged to yield

$$C^{m}(r) = \frac{1}{N - m + 1} \sum_{j=1}^{N - m + 1} C_{j}^{m}(r)$$
(3.13)

and the sample entropy is obtained as

SampEn
$$(m, r, N) = \ln (C^m(r)/C^{m+1}(r)).$$
 (3.14)

The default values set for the embedding dimension m and for the tolerance parameter r in the software are the same as those for the approximate entropy calculation. Both ApEn and SampEn are estimates for the negative natural logarithm of the conditional probability that a data of length N, having repeated itself within a tolerance r for m points, will also repeat itself for m+1 points. SampEn was designed to reduce the bias of ApEn and has a closer agreement with the theory for data with known probabilistic content [21].

3.3.4 Multiscale entropy (MSE)

Multiscale entropy (MSE) is an extension of SampEn in the sense that it incorporates two procedures [8]

- 1. A course-graining process is applied to the RR interval time series. Multiple course-grained time series are constructed for the time series by averaging the data points within non-overlapping windows of increasing length τ , where τ represents the scale factor and is selected to range between $\tau = 1, 2, \ldots, 20$. The length of each course-grained time series is N/τ , where N is the number of RR intervals in the data. For scale $\tau = 1$, the course-grained time series is simply the original beat-to-beat RR interval time series.
- 2. SampEn is calculated for each course-grained time series. SampEn as a function of the scale factor produces the MSE. MSE for scale factor $\tau=1$ returns standard SampEn (computed from the original data points).

3.3.5 Detrended fluctuation analysis

Detrended fluctuation analysis (DFA) measures the correlation within the signal. The correlation is extracted for different time scales as follows [37]. First, the RR interval time series is integrated

$$y(k) = \sum_{j=1}^{k} (RR_j - \overline{RR}), \quad k = 1, \dots, N$$
(3.15)

where RR is the average RR interval. Next, the integrated series is divided into segments of equal length n. Within each segment, a least squares line is fitted into the data. Let $y_n(k)$ denote these regression lines. Next the integrated series y(k) is detrended by subtracting the local trend within each segment and the root-mean-square fluctuation of this integrated and detrended time series is calculated by

$$F(n) = \sqrt{\frac{1}{N} \sum_{k=1}^{N} (y(k) - y_n(k))^2}.$$
 (3.16)

This computation is repeated over different segment lengths to yield the index F(n) as a function of segment length n. Typically F(n) increases with segment length. A linear relationship on a double log graph indicates presence of fractal scaling and the fluctuations can be characterized by scaling exponent α (the slope of the regression line relating log F(n) to log n. Different values of α indicate the following

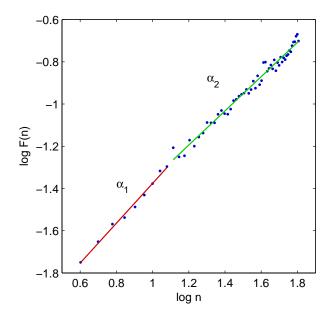


Figure 3.2: Detrended fluctuation analysis. A double log plot of the index F(n) as a function of segment length n. α_1 and α_2 are the short term and long term fluctuation slopes, respectively.

 $\alpha = 1.5$: Brown noise (integral of white noise)

 $1 < \alpha < 1.5$: Different kinds of noise

 $\alpha = 1$: 1/f noise

 $0.5 < \alpha < 1$: Large values are likely to be followed by large value and vice versa

 $\alpha = 0.5$: white noise

 $0 < \alpha < 0.5$: Large value is likely to be followed by small value and vice versa

Typically, in DFA the correlations are divided into short-term and long-term fluctuations. In the software, the short-term fluctuations are characterized by the slope α_1 obtained from the $(\log n, \log F(n))$ graph within range $4 \le n \le 16$ (default values). Correspondingly, the slope α_2 obtained by default from the range $16 \le n \le 64$ characterizes long-term fluctuations, see Fig. 3.2.

3.3.6 Correlation dimension

Another method for measuring the complexity or strangeness of the time series is the correlation dimension which was proposed in [15]. The correlation dimension is expected to give information on the minimum number of dynamic variables needed to model the underlying system and it can be obtained as follows.

Similarly as in the calculation of approximate and sample entropies, form length m vectors u_j

$$u_i = (RR_i, RR_{i+1}, \dots, RR_{i+m-1}), \quad j = 1, 2, \dots, N - m + 1$$
 (3.17)

and calculate the number of vectors u_k for which $d(u_i, u_k) \leq r$, that is

$$C_j^m(r) = \frac{\text{nbr of } \left\{ u_k \mid d(u_j, u_k) \le r \right\}}{N - m + 1} \quad \forall k$$
(3.18)

where the distance function $d(u_i, u_k)$ is now defined as

$$d(u_j, u_k) = \sqrt{\sum_{l=1}^{m} (u_j(l) - u_k(l))^2}.$$
(3.19)

Next, an average of the term $C_i^m(r)$ is taken

$$C^{m}(r) = \frac{1}{N-m+1} \sum_{j=1}^{N-m+1} C_{j}^{m}(r)$$
(3.20)

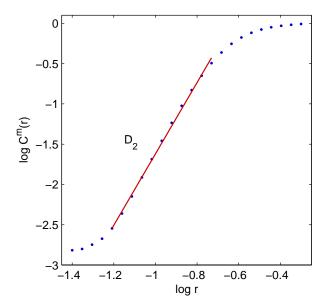


Figure 3.3: Approximation of the correlation dimension D_2 from the $(\log r, \log C^m(r))$ plot.

which is the so-called correlation integral. The correlation dimension D_2 is defined as the limit value

$$D_2(m) = \lim_{r \to 0} \lim_{N \to \infty} \frac{\log C^m(r)}{\log r}.$$
(3.21)

In practice this limit value is approximated by the slope of the regression curve (log r, log $C^m(r)$) [19]. The slope is calculated from the linear part of the log-log plot, see Fig. 3.3. The slope of the regression curves tend to saturate on the finite value of D_2 when m is increased. In the software, a default value of m = 10 was selected for the embedding.

3.3.7 Recurrence plot analysis

Yet another approach, included in the software, for analyzing the complexity of the time series is the so-called *recurrence plot* (RP) analysis. In this approach, vectors

$$u_j = (RR_j, RR_{j+\tau}, \dots, RR_{j+(m-1)\tau}), \quad j = 1, 2, \dots, N - (m-1)\tau$$
 (3.22)

where m is the embedding dimension and τ the embedding lag. The vectors u_j then represent the RR interval time series as a trajectory in m dimensional space. A recurrence plot is a symmetrical $[N-(m-1)\tau]\times[N-(m-1)\tau]$ matrix of zeros and ones. The element in the j'th row and k'th column of the RP matrix, i.e. RP(j,k), is 1 if the point u_j on the trajectory is close to point u_k . That is

$$RP(j,k) = \begin{cases} 1, & d(u_j - u_k) \le r \\ 0, & \text{otherwise} \end{cases}$$
 (3.23)

where $d(u_j, u_k)$ is the Euclidean distance given in (3.19) and r is a fixed threshold. The structure of the RP matrix usually shows short line segments of ones parallel to the main diagonal. The lengths of these diagonal lines describe the duration of which the two points are close to each other. An example RP for HRV time series is presented in Fig. 3.4. Methods for quantifying recurrence plots were proposed in [47]. The methods included in this software are introduced below.

In the software the following selections were made. The embedding dimension and lag were selected to be m=10 (default value) and $\tau=1$ (fixed), respectively. The threshold distance r was selected to be \sqrt{m} SD (default value), where SD is the standard deviation of the RR time series. The selection are similar to those made in [9].

The first quantitative measure of RP is the recurrence rate (REC) which is simply the ratio of ones and zeros in the RP matrix. The number of elements in the RP matrix for $\tau=1$ is equal to N-m+1 and the recurrence rate is simply given as

$$REC = \frac{1}{(N-m+1)^2} \sum_{j,k=1}^{N-m+1} RP(j,k).$$
 (3.24)



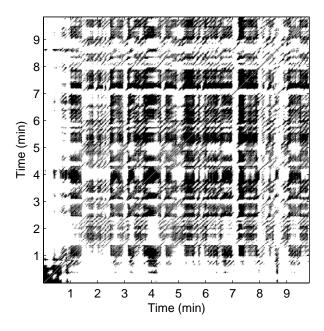


Figure 3.4: Recurrence plot matrix for HRV time series (black = 1 and white = 0).

The recurrence rate can also be calculated separately for each diagonal parallel to the line-of-identity (main diagonal). The trend of REC as a function of the time distance between these diagonals and the line-of-identity describes the fading of the recurrences for points further away.

The rest of the RP measures consider the lengths of the diagonal lines. A threshold $l_{\min} = 2$ is used for excluding the diagonal lines formed by tangential motion of the trajectory. The maximum line length is denoted l_{\max} and its inverse, the divergence,

$$DIV = \frac{1}{l_{\text{max}}} \tag{3.25}$$

has been shown to correlate with the largest positive Lyapunov exponent [46]. The average diagonal line length, on the other hand, is obtained as

$$l_{\text{mean}} = \frac{\sum_{l=l_{\text{min}}}^{l_{\text{max}}} l N_l}{\sum_{l=l_{\text{min}}}^{l_{\text{max}}} N_l}$$
(3.26)

where N_l is the number of length l lines. The determinism of the time series is measured by the variable

$$DET = \frac{\sum_{l=l_{\min}}^{l_{\max}} lN_l}{\sum_{j,k=1}^{N-m+1} RP(j,k)}.$$
(3.27)

Finally, the Shannon information entropy of the line length distribution is defined as

$$ShanEn = -\sum_{l=l_{min}}^{l_{max}} n_l \ln n_l$$
(3.28)

where n_l is the number of length l lines divided by the total number of lines, that is

$$n_l = \frac{N_l}{\sum_{l'=l_{\min}}^{l_{\max}} N_{l'}}.$$
(3.29)

3.4 Summary of HRV parameters

The presented time-domain, frequency-domain and nonlinear measures of HRV calculated by the software are summarized in Table 3.1. For each measure, preferred units and a short description is given. In addition, a reference to the equation in which the specific measure is defined is given when possible and related references are given for some of the measures.



Table 3.1: Summary of the HRV measures calculated by the software $\,$

	Measure	Units	Description	References
Time-Domain	RR STD RR (SDNN) HR STD HR RMSSD NN50 pNN50	[ms] [ms] [1/min] [1/min] [ms]	The mean of RR intervals Standard deviation of RR intervals [Eq. (3.1)] The mean heart rate Standard deviation of intantaneous heart rate values Square root of the mean squared differences between successive RR (3.3)] Number of successive RR interval pairs that differ more than 50 ms NN50 divided by the total number of RR intervals [Eq. (3.4)]	intervals [Eq.
r	HRV triangular index TINN	[ms]	The integral of the RR interval histogram divided by the height of t [44] Baseline width of the RR interval histogram	he histogram [44]
-Domain	Peak frequency Absolute power Relative power	[Hz] [ms ²] [%]	VLF, LF, and HF band peak frequencies Absolute powers of VLF, LF, and HF bands Relative powers of VLF, LF, and HF bands $VLF [\%] = VLF [ms^2]/total power [ms^2] \times 100\%$ $LF [\%] = LF [ms^2]/total power [ms^2] \times 100\%$	
Frequency-Domain	Normalized power	[n.u.]	HF [76] = HF [ms²]/total power [ms²] × 100% Powers of LF and HF bands in normalized units LF [n.u.] = LF [ms²]/(total power [ms²] - VLF [ms²]) HF [n.u.] = HF [ms²]/(total power [ms²] - VLF [ms²]) Ratio between LF and HF band powers	
Nonlinear	SD1, SD2 ApEn SampEn D_2 DFA α_1 α_2 RPA	[ms]	The standard deviation of the Poincaré plot perpendicular to (SD1) and the line-of-identity Approximate entropy [Eq. (3.11)] Sample entropy [Eq. (3.14)] Correlation dimension [Eq. (3.21)] Detrended fluctuation analysis: Short term fluctuation slope Long term fluctuation slope Recurrence plot analysis:	1 along (SD2) [6, 7] [41, 14] [41] [17, 19] [37, 38]
	Lmean Lmax REC DET ShanEn	[beats] [beats] [%] [%]	Mean line length [Eq. (3.26)] Maximum line length Recurrence rate [Eq. (3.24)] Determinism [Eq. (3.27)] Shannon entropy [Eq. (3.28)]	[#1, 0, #0]

Chapter 4

Software description

4.1 Input data formats

Kubios HRV supports the following data formats:

1. 2. 3. 4.	Biopac AcqKnowledge files (Biopac Systems Inc.) European data format (EDF) files General data format (GDF) files ECG ASCII data files	(*.acq) (*.edf) (*.gdf) (*.txt,*.dat)
5. 6. 7. 8.	Polar HRM files (Polar Electro Ltd.) Suunto SDF/STE files (Suunto Ltd.) Garmin FIT files (Garmin Ltd.) RR interval ASCII files	(*.hrm) (*.sdf,*.ste) (*.fit) (*.txt,*.dat)
9. 10.	Custom ASCII data files Kubios HRV Matlab MAT files	(*.txt,*.dat) (*.mat)

The three first ones (Biopac ACQ, EDF and GDF) are binary data formats. When any of these data format files are read to the software, Kubios HRV automatically tries to determine the ECG channel from the channel labels. If the ECG channel cannot be determined (or more than one channels are identified as ECG channels), the software prompts the user to select the appropriate channel. Due to internal design restrictions of Kubios HRV, the channel labels should only contain alphabets, numbers, and underscores. If the channel labels contain other characters, such as spaces or plus signs, etc., these characters are changed to underscores. Furthermore, the channel label should start with an alphabet. If this is not the case, "Ch." is added to the beginning of the channel label.

In addition to the above binary formats, Kubios HRV supports also ASCII ECG data which must be given in the form

Type 1	Type 2	
-0.173	0	-0.173
-0.119	0.002	-0.119
-0.025	0.004	-0.025
0.091	0.006	0.091
0.218	0.008	0.218
:	:	:

where the first column on the second format type is the time scale in seconds for the ECG data. The sampling rate of this example file is, thus, 500 Hz. If ECG data is given according to the first type, user is requested to enter the sampling rate manually. In addition to these ECG file support options, Kubios HRV supports three RR interval file formats as described below.

Kubios HRV supports the following RR interval file formats. First of all, data of three commonly used heart rate monitor manufacturers are supported. These are SUUNTO SDF/STE, POLAR HRM

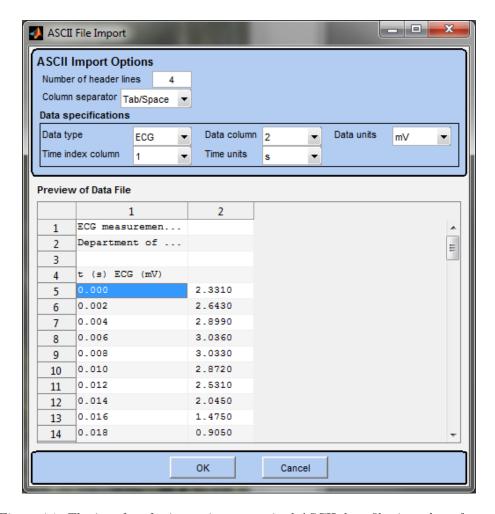


Figure 4.1: The interface for importing customized ASCII data files into the software.

files and GARMIN FIT files. When analyzing data of these devices it should however be noted that the RR intervals must be measured/stored in beat-to-beat! If only averaged data (e.g. HR values at every 5 seconds) are stored, one can not perform HRV analyses. In addition Polar, Suunto and Garmin file formats, a support for plain RR interval ASCII text files is provided. The input ASCII file can include RR interval values in one or two column format. That is, The RR interval values can be given as

Type 1	\mathbf{Typ}	pe 2
0.759	0.759	0.759
0.690	1.449	0.690
0.702	2.151	0.702
0.712	2.863	0.712
0.773	3.636	0.773
:	:	:

So in the second type of input the first column includes the time indexes of R wave detections (zero time for the first detection) and second column the RR interval values. The RR interval values above are given in seconds, but millisecond values can also be given.

In addition to above file formats, a custom ASCII file option is also provided. Using this option you can import ASCII files including header lines and/or several data columns. Once you have selected an input file, an interface for importing the file into Kubios is opened. This interface is shown in Fig. 4.1. Through this interface you can specify the following required details corresponding to your data file

- Number of header lines
- Column separator (tab/space, comma, or semicolon)



- Data type (ECG or RR)
- Data column (the ordinal number of data column)
- Data units (μV , V or mV for ECG / ms or s for RR)
- Time index column (the ordinal number of time indexes)
- Time units (units of time indexes in ms, s or date/time format)
- ECG sampling rate in Hz (if no time index column defined for ECG).

Once you have specified the above values for your file, press OK to proceed to analysis.

Finally, the software supports also MATLAB® MAT files saved by the software itself. When you are using Kubios HRV, you can save the analysis results also into a Matlab MAT file as described in Section 4.3.3. These result files include all the analysis results and analysis parameters, exactly as they where when you saved the results. In addition, these files include the raw data (ECG or RR data). Therefore, you are able to return to already analyzed data simply by opening the saved MAT file again in Kubios HRV. The software will open with the settings that you have used when saving the results (e.g. including the selected analysis samples). So this is the simplest way to return to previously analyzed data and perhaps change some analysis parameter and re-compute the results. In addition, the MAT file are also useful for anyone working with Matlab.

4.2 The user interface

The developed HRV analysis software is operated with a graphical user interface. This user interface window is shown in Fig. 4.2. The user interface is divided into four segments: 1) the RR interval series options segment on the top left corner, 2) the data browser segment on the top right corner, 3) the analysis options segment on the bottom left corner, and 4) the results view segment on the bottom right corner. Each of these segments are described in Sections 4.2.1, 4.2.2, 4.2.3, and 4.2.4, respectively.

4.2.1 RR interval series options

The RR interval series options shown in Fig. 4.3 include three functions: Artifact correction, Samples for analysis, and Remove trend components. The artifact correction options can be used to correct artifacts from a corrupted RR interval series. The user can select between very low, low, medium, strong, and very strong correction levels. In addition, a custom level in seconds can be set. The different correction levels define thresholds (very low=0.45 sec, low=0.35 sec, medium=0.25 sec, strong=0.15 sec, very strong=0.05 sec) for detecting RR intervals differing "abnormally" from the local mean RR interval. For example, the correction level "medium" will identify all RR intervals which are bigger/smaller than 0.25 seconds compared to the local average. Furthermore, the above correction thresholds are for 60 beats/min heart rate, for higher heart rates the thresholds are smaller (because the variability is expected to decrease when HR increases). The corrections to be made on the RR series are displayed on the RR interval axis. To make the corrections press the Apply button. A piecewise cubic spline interpolation method is used in the corrections. You can reverse the correction by pressing the Undo button or by selecting none as the correction level. It should be noted that artifact correction generates missing or corrupted values into the RR series by interpolation and can cause distortion into the analysis results. Note that if ECG is measured, the corrections should always be done by editing the R-peak marks in the ECG data as described in Section 4.2.2.

An example of artifact correction can be seen in Fig. 4.4. In this case, the analyzed RR interval sample includes two clear artifacts. In order to remove these artifacts a medium level correction was selected. The effect of correction can be verified from the user interface, i.e. the corrected series is displayed on top of the raw RR interval series as can be seen from Fig. 4.4 (a). The percentage of corrected beats is also displayed on the right side of the RR series axis. The correction level can be accepted and the correction performed by pressing the Apply button. The corrected series is shown in Fig. 4.4 (b). As can be seen from Figs. 4.4 (a) and (b), the correction of just few artifacts has a very significant effect on the time-domain analysis results. Thus, even single artifacts should always be taken care of prior to HRV analysis.

In the Samples for analysis options the part(s) of the RR interval series to be analyzed can be modified by adding or removing samples and by changing the start time or length of the sample. If more than





Figure 4.2: The graphical user interface of the developed HRV analysis software.

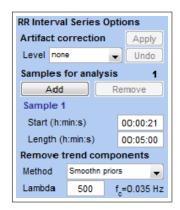


Figure 4.3: The RR interval series options segment of the user interface.

one sample is selected, the analysis can be done either for the single samples separately or by merging the samples into one long sample before analysis. This selection is visible under the RR series axis when multiple samples are selected. The starting point and length of the samples can also be changed by moving/resizing the patch over the RR series as described in Section 4.2.2. This section also describes how to add/remove samples to/from RR series axes.

Sometimes the RR interval time series includes a disturbing low frequency baseline trend component. Detrending options can be used to remove this kind of trend components. Detrending options include removal of the first, second, or third order linear trend or the trend can be removed using a method called smoothness priors which was presented in [43]. In the smoothness priors method, the smoothness of the removed trend can be adjusted by editing the Lambda value. The smoothness priors method is basically a time-varying high pass filter and its cut-off frequency can be adjusted with the Lambda parameter (the bigger the value of Lambda the smoother is the removed trend). The estimated cut-off frequency for the given Lambda value is presented next to the Lambda value edit box. In addition, the trend to be

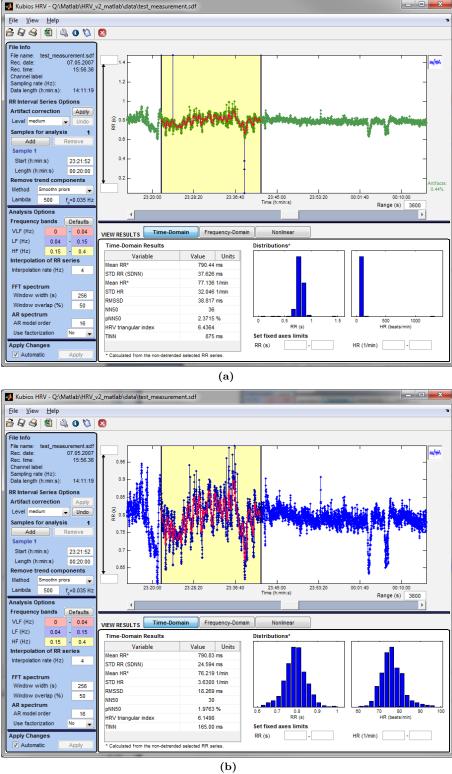


Figure 4.4: Artifact correction: (a) the artifact corrected series is visualized on top of the raw RR interval series. (b) Corrected RR interval series.

removed from the RRI series is shown over the selected part of the RR series as a red line.

4.2.2 Data browser

The data browser segment shown in Fig. 4.5 displays the measured ECG signal and the extracted RR interval series. It should be noted that if only RR interval data is given as input the ECG axis will not



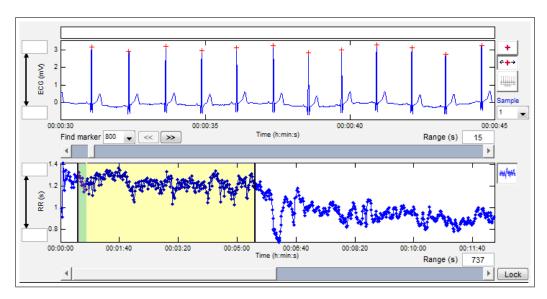


Figure 4.5: The data browser segment of the user interface.

be displayed and the RR series axis will be bigger in size. The ECG and RR interval data can be scrolled with the two sliders. The position of the ECG axis is displayed as a green patch in the RR axis. This patch can also be moved with the left mouse button. The range of both axes can be changed by editing the Range values and also the Y-limits of the axes can be manually changed by editing the edit boxes on the left hand side of the axes. The ECG and RR interval axes can also be scrolled together by locking the axes by pressing the "Lock" button on the right side of the RR axis slider.

In addition to the visualization of the ECG and RR interval data, the main function of this segment is to enable correction of corrupted RR interval values. This can be done in two ways. If only RR data is available, the artifact corrections described in Section 4.2.1 are displayed in the RR axis. If the ECG is measured, these corrections can be made by editing the misdetected R-peak as follows. Each detected R-peak is marked in the ECG axis with a "+" mark. Each mark can be moved or removed by right clicking it with the mouse (see Fig. 4.5). In addition, new R-peak markers can be added by either right clicking some other marker and selecting Add or by pressing the uppermost button on the right hand side of the ECG axis. Moved or added R-peak markers are by default snapped to closed ECG maximum, but manual positioning can also be achieved by pressing the middle button on the right hand side of the ECG axis. The changes made in R-peak markers will be automatically updated to RR interval series.

The selected sample(s) (yellow patches in the RR axis) can be modified with mouse as follows. Each sample can be moved by grabbing it from the middle with the left mouse button and resized by grabbing it from the left or right edge. You can also add a new sample to a specific location in the RR series by right clicking the RR axis. The new sample will start from the clicked time instant and the length of the new sample is by default same as the previous sample. After right clicking the RR axis a small popup window opens in which the sample start time and length can be accepted/modified. When more than one samples are selected, a sample can be removed by right clicking it with the mouse.

In addition, the data browser segment includes buttons for displaying a printout of the ECG recording (on the right hand side of the ECG axis), moving the ECG axis view to the beginning of a selected sample (on the right hand side of the ECG axis), scrolling the markers of the recording session (below the ECG axis), and changing the RR series display mode (on the right hand side of the RR axis). An example of the ECG printout is shown in Fig. 4.6. When clicking on the button for displaying a printout of the ECG recording, a popup window will appear in which you can select the range for the ECG to be printed (e.g. the whole recording or the range of the analysed sample). In addition, you can adjust "print speed" in mm/sec of the ECG in this popup window. Once you have defined the range for ECG printout and clicked the OK button, the ECG signal is displayed in a similar window as the report sheet and has, thus, e.g. the same kind of exporting functions (see Section 4.3.2 for details).

4.2.3 Analysis options

The analysis options segment shown in Fig. 4.7 includes three subcategories: Frequency bands, Interpolation of RR series, and Spectrum estimation. All of these options are concerned with frequency-domain



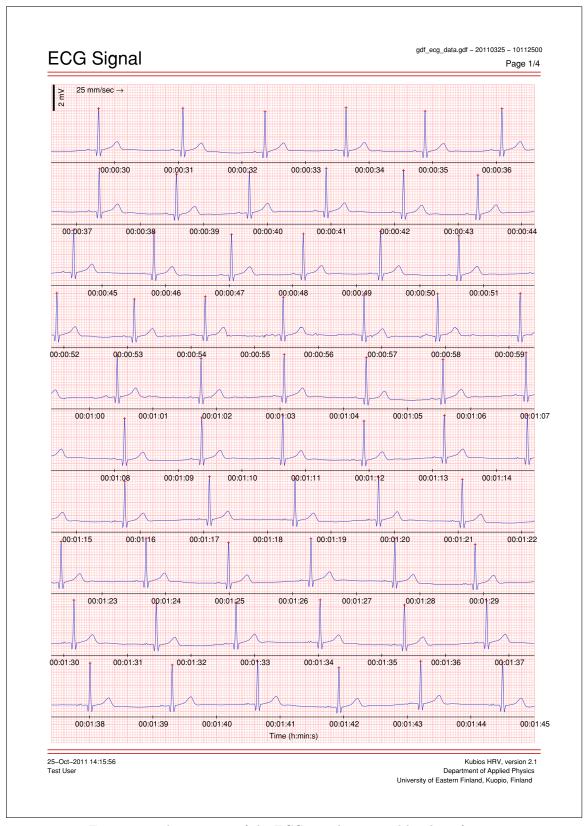


Figure 4.6: The printout of the ECG signal generated by the software.

analysis.

The very low frequency (VLF), low frequency (LF), and high frequency (HF) bands of HRV frequency-domain analysis can be adjusted by editing the VLF, LF, and HF values. The default values for the bands are VLF: 0–0.04 Hz, LF: 0.04–0.15 Hz, and HF: 0.15–0.4 Hz according to [44]. The default values for the bands can be restored by pressing the Defaults button.

The RR interval time series is an irregularly time sampled series as discussed in Section 2.2 and, thus,



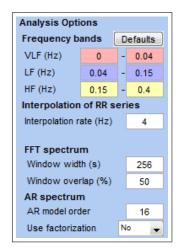


Figure 4.7: The analysis options segment of the user interface.

spectrum estimation methods can not be applied directly. In this software, this problem is solved by using interpolation methods for converting the RR series into equidistantly sampled form. As the interpolation method a piecewise cubic spline interpolation is used. The sampling rate of the interpolation can be adjusted by editing the Interpolation rate value. By default a 4 Hz interpolation is used.

The spectrum for the selected RR interval sample is calculated both with Welch's periodogram method (FFT spectrum) and with an autoregressive modeling based method (AR spectrum). In the Welch's periodogram method, the used window width and window overlap can be adjusted by editing the corresponding value. The default value for window width is 256 seconds and the default overlap is 50 % (corresponding to 128 seconds). In the AR spectrum, there are also two options that can be selected. First, the order of the used AR model can be selected. The default value for the model order is 16, but the model order should always be at least twice the number of spectral peaks in the data. The second option is whether or not to use spectral factorization in the AR spectrum estimation. In the factorization the Ar spectrum is divided into separate components and the power estimates of each component are used for the band powers. The factorization, however, has some serious problems which can distort the results significantly. The main problems are the selection of the model order in such a way that only one AR component will result in each frequency band and, secondly, negative power values can result for closely spaced AR components. Thus, the selection of not to use factorization in AR spectrum is surely more robust and in that sense recommended.

4.2.4 Results view

The results for the selected RR interval sample are displayed in the results view segment. The results are divided into time-domain, frequency-domain and nonlinear results. The results of each section are displayed by pressing the corresponding button on the top of the results view segment. The results are by default updated automatically whenever any one of the the sample or analysis options that effect on the results is changed. The updating of the results can be time consuming for longer samples and in that case it might be useful to disable the automatic update by unchecking the Automatic check box in the bottom left corner of the user interface. When unchecked, one or more changes to options can be made without updating breaks and when finished with changes the Apply button can be pressed to update the results.

The time-domain results view shown in Fig. 4.8 displays the time-domain variables in a table and the RR interval and heart rate histograms in the two axes. Most of the results are calculated from the detrended RR series (if detrending is applied), but there are two obvious exceptions (i.e. mean RR interval and mean HR) which are marker with the * symbol.

The frequency-domain results view shown in Fig. 4.9 displays the results for both FFT and AR spectrum estimation methods. Both methods are applied to the detrended RR series. The spectra of the two methods are presented in the two axes (FFT spectrum on the left and AR spectrum on the right). The frequency axes of the spectra are fixed to range from 0 Hz to the upper limit of HF band plus 0.1 Hz. Thus, for the default frequency band settings the frequency axis range is 0–0.5 Hz. The power axes of the spectra, on the other hand, can be adjusted with the options on the upper right corner of the frequency-domain results view. The power axes can be selected to have either common or separate upper

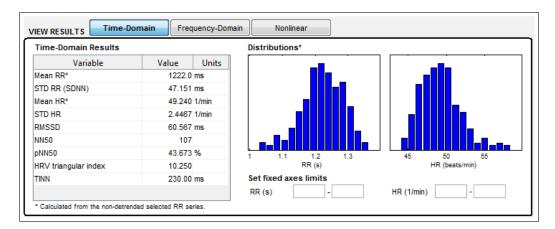


Figure 4.8: The results view segment of the user interface: time-domain results view selected.

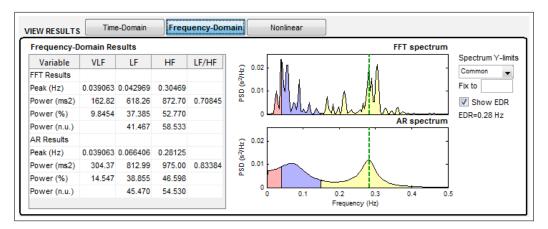


Figure 4.9: The results view segment of the user interface: frequency-domain results view selected.

Y-limits. If common Y-limit is selected, it can also be entered manually into the edit box below the selection button. The selected power axis options apply also for the report sheet. The results for both spectra are displayed in tables below the corresponding spectrum axes. If ECG is measured, an estimate of the respiration frequency is also computed. This estimate, i.e. electrocardiogram derived respiration (EDR) is shown as a vertical line in both spectrum estimates. The EDR value is also shown on the right below the spectrum Y-limit options.

The nonlinear results view shown in Fig. 4.10 displays all the calculated nonlinear variables in one table. All the variables are calculated from the original non-detrended RR series. The Poincaré plot and the DFA results are also presented graphically in the two axes. In the Poincaré plot (left hand axis), the successive RR intervals are plotted as blue circles and the SD1 and SD2 variables obtained from the ellipse fitting technique are presented (for details see Section 3.3.1). In the DFA plot (right hand axis), the detrended fluctuations F(n) are presented as a function of n in a log-log scale and the slopes for the short term and long term fluctuations α_1 and α_2 , respectively, are indicated (for details see Section 3.3.5).

4.2.5 Menus and toolbar buttons

The user menus and toolbar buttons are located on the upper left hand corner of the user interface. There are all together three user menus and seven toolbar buttons. The toolbar button icons and their actions are given below

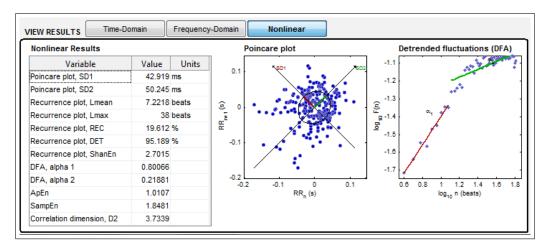


Figure 4.10: The results view segment of the user interface: nonlinear results view selected.



Open new data file button is for opening a new data file for analysis. If the results of the current analysis have not been saved, user is prompted to do so.



Save results button is for saving the analysis results. The results can be saved in ASCII, PDF, and MATLAB® MAT file format (see Section 4.3 for details).



Print results button is for printing the current results without opening report sheet windows.



Report sheet button opens one or several report sheet windows which include all the analysis results (see Section 4.3.2 for details).



Edit preferences button opens a preferences window in which you can, e.g., change the default values for analysis options (see Section 4.4 for details).



About HRV analysis software button opens the about dialog of the software which includes the version number and contact information. Also the Kubios HRV End User License Agreement can be viewed in the about dialog.



Open Kubios HRV User's Guide button opens the Kubios HRV User's Guide (this document) PDF-file using the default PDF viewer of the system.



Close file button closes the current data file. If the results of the current analysis have not been saved, user is prompted to do so.

All the above actions are also available on the user menus. The File menu includes Open, Save Results, Save Results As, Print Results, Edit Preferences, Close, and Quit commands. The Open, Save Results, Edit Preferences, and Close commands work exactly as the corresponding toolbar buttons. The difference between the Save and Save As commands is that when the results have already been saved, the Save command automatically overwrites these results, whereas the Save As command asks the user for a new file name. The Quit command of the File menu is for exiting from the software. The View menu includes Markers menu and Report sheet command. The latter works as the corresponding toolbar button. The Markers menu, on the other hand, is for displaying possible stimuli or event markers presented in the experimental procedure and stored in the data file. If no markers are found from the data file the Markers menu will be disabled. Finally, the Help menu includes the About HRV Analysis Software command which opens the same about dialog as the corresponding toolbar button.

4.3 Saving the results

The analysis results can be saved by selecting Save Results or Save Results As from the File menu or by pressing the save button on the toolbar. This will open a file save dialog in which the saving type can be selected. There are three different types in which the results can be saved. That is, the results can be

written in an ASCII text file for further inspection, the report sheets generated from the results can be saved in a PDF-file, or the results can be saved in a MATLAB® MAT-file.

4.3.1 ASCII-file

When the ASCII text file is selected for the saving type, the numeric results of the analysis will be written in an ASCII text file. The resulting text file includes the following information in the enumerated order.

- 1. Software, user, and data file informations
- 2. Used analysis parameters
- 3. Samples selected for analysis
- 4. Time-domain results
- 5. Frequency-domain results
- 6. Nonlinear results
- 7. RR interval data and spectrum estimates

The columns of the file are separated with semicolons so that the results could easily be imported to, e.g., spreadsheet programs such as the Microsoft Excel[®] for further inspection.

Note that there is also an alternative for the ASCII-file format. The analysis results can be also saved in an SPSS friendly format, where all the parameter values are saved in one row. The column headers are named according to the parameter names, but in SPSS compatible strings. If you have analyzed more than one sample, the results for different samples are presented in separate rows (one row per analyzed sample). This functionality was implemented in order the user's to be able to easily construct SPSS compatible text files for their patient data. That is, if you are analyzing data of several patients, just save the "SPSS fiendly" text files for each patient, and then finally copy paste all the results in one text file with the column headers (one row for each patient). This text file can then be easily imported to SPSS. NOTE: you need to select this alternative format from the Preferences under Report settings (see Section 4.4) because by default it's not selected.

4.3.2 Report sheet

The software generates a printable report sheet which present all the analysis results. The report sheet, shown in Fig. 4.11, includes all the time-domain, frequency-domain, and nonlinear analysis results. The RR interval data and the sample selected for analysis are presented on the two axes on top of both sheet and the analysis results below them. If multiple analysis samples have been selected, a report sheet is generated for each sample.

When Save Results have been selected, the report sheet(s) can be saved in a single PDF-file by selecting Report figure as the saving type in the save dialog. In this case, the report sheet(s) will not be displayed, but just saved in the selected PDF-file. If you wish to view the report sheet(s) and/or to export it into some other file format choose Report sheet from the View menu or just press the corresponding toolbar button. This will open the report sheet windows for view.

The report sheet window includes 7 toolbar buttons and File and Page menus on the upper left hand corners of the windows. The toolbar button icons and their actions are given below



Print button opens a print dialog from which the report sheet can sent to the selected printer.



Export all pages to PDF-file button is for exporting all report sheets into a single PDF-file.



Zoom in button if for zooming in (magnifying) the report sheet.



Zoom out button is for zooming out the report sheet.



Reset to original size button can be used to restore the original zoom level. This also resets the size of the corresponding report sheet window to its original size.



Move visible area button is for moving the visible area of the zoomed report sheet in the report window (just grab the sheet with mouse and drag it to the desired direction).



Close button is for closing the report sheet.



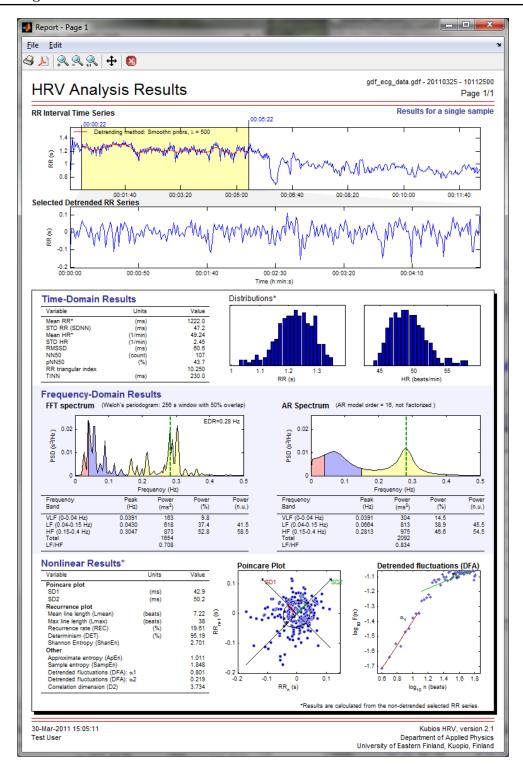


Figure 4.11: The first report sheet including all the time-domain, frequency-domain, and nonlinear analysis results calculated by the software.

The File menu includes Export All to PDF, Print Current Page, Print All Pages, Close, and Close All commands. The Export All to PDF, Print All Pages, and Close commands are also given as toolbar buttons described above. The last command Close All can be used for closing all report sheets simultaneously. The Edit menu (Windows version only) contains Copy to Clipboard option, which copies the contents of the corresponding report sheet window to the Windows clipboard. This can be used to quickly copying the report sheet as an image into another program. The Page menu includes commands for changing for the previous or the next report sheet page and for changing the sheet by its page number. However, the Page menu is not shown if only one report sheet window is open.

4.3.3 Matlab MAT-file

In addition to saving the numeric results into an ASCII text file or saving the report sheet(s) in a PDF-file, the analysis results can also be saved in a MATLAB® MAT-file (compatible with MATLAB® R12 or higher). The MAT-file includes a single structured array variable named Res. The Res variable includes the numeric results as well as the RR interval data and all the analysis options. This saving option is aimed for MATLAB users and makes the further analysis or processing of the HRV data in MATLAB much easier. The Res structure includes four fields which are shortly described as follows

f_name: File name of the analyzed data filef_path: Full path for the analyzed data file

CNT: Basic information of the data file (the field name refers to Neuroscan CNT-file

for historical reasons)

HRV: Used analysis options, RR interval data, and all analysis results.

The HRV field is clearly the most essential one of these fields. The HRV field includes six fields the contents of which are shortly described as follows

Param: The analysis options used in the calculation of the results

Data: The RR interval data

Statistics: Time-domain analysis results
Frequency: Frequency-domain analysis results

NonLinear: Nonlinear analysis results

The variable names of the different fields are more or less self-descriptive and are not documented here.

4.4 Setting up the preferences

All the analysis options that can be adjusted in the user interface have some default values. These preference values will be used every time the program is started. Any changes made on these values in the user interface only apply for the current session. The preference values are designed to be more or less suitable for short-term HRV recordings and may sometimes need to be redefined. This can be done by selecting Edit Preferences from the File menu or by pressing the corresponding toolbar button. This will open the preferences window in which the preference values can be redefined. The preferences are divided into four categories: User information, Analysis options, Advanced settings, and Report settings.

In the **User information category** shown in Fig. 4.12 you can set up your personal contact information (Name, Department, and Organization). This information will only be included in the bottom left corner of the report sheet and in the beginning of the ASCII text file including the analysis results. That is, the user information is meant just for indicating the person who has carried out the analysis.

The **Analysis options category** shown in Fig. 4.13 includes some basic analysis options. The default input data type can be set to one of the file formats mentioned in Section 4.1 and the selected data type will be used as default every time a new data file is opened. In addition, the analysis options category includes RR interval samples, RR interval detrending, HRV frequency bands, and Update analysis results options which have already been described in Sections 4.2.1, 4.2.3, and 4.2.4.

The Advanced settings category shown in Figa. 4.14 and 4.15 is divided into two pages. The first page includes QRS detection and Spectrum estimation options. In the QRS detection options you can set up the prior guess for the average RR interval. By default this prior guess is estimated automatically. This may not, however, always work (e.g. for some animal data) in which case the prior guess for the RR interval value should be fixed to the supposed value. The spectrum estimation options include one additional option compared to those described in Section 4.2.3, i.e. points in frequency-domain option. The points in frequency-domain is given as points/Hz and corresponds by default to the window width of the FFT spectrum. If spectrum interpolation is desired the points in frequency-domain can be increased.

The second page of the Advanced settings category includes options for nonlinear analysis. The embedding dimension m and the tolerance value r used in for the computation of Approximate entropy (ApEn) and Sample entropy (SampEn) can be modified. Note that the tolerance value is adjusted in relation to the standard deviation of the RR interval data. Next, limits of the short-term (N1) and long-term fluctuations used in the Detrended fluctuation analysis (DFA) can be modified. Finally, the



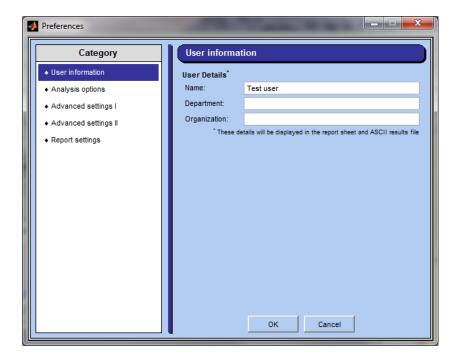


Figure 4.12: Set up preferences window of the software: User information category.

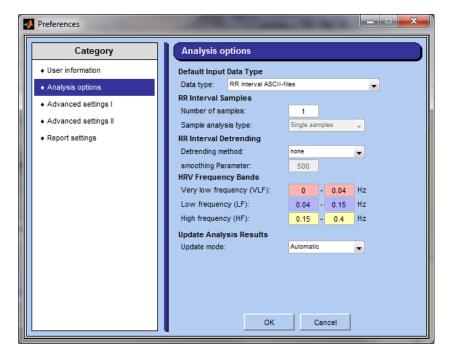


Figure 4.13: Set up preferences window of the software: Analysis options category.

embedding dimension used both in the computation of the Correlation dimension (D_2) and in the Recurrence plot analysis (RPA), and the threshold level used in RPA, can be modified. For more information on the meaning of these different options see Section 3.3.

The **Report settings category** shown in Fig. 4.16 includes the following options. The paper size of the report sheet can be changed between A4 $(210\times297 \text{ mm})$ and Letter $(8.5\times11 \text{ inch})$ size. The default paper size is A4. In addition, the field delimiter and decimal point used when saving the results in an ASCII file can be selected. Here you can also select to save the results in an "SPSS friendly" format described in Section 4.3.1. The Custom Print Command option allows the use of an external program to print the report sheets in PostScript format.

All modifications for the preferences are saved by pressing the OK button. Note that the OK button



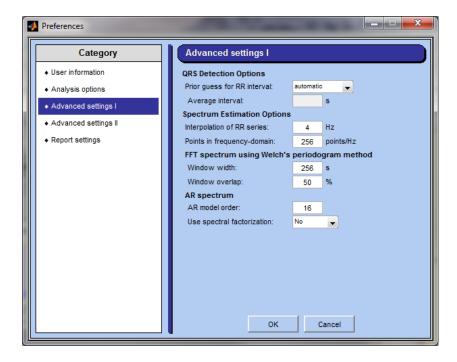


Figure 4.14: Set up preferences window of the software: Advanced settings category I.

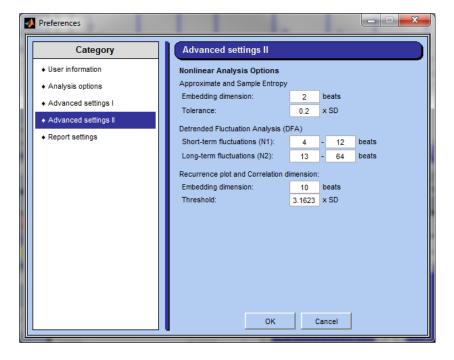


Figure 4.15: Set up preferences window of the software: Advanced settings category II.

saves the preferences, but they will be applied only in the next session. A session is considered to be ended when the program is restarted or Close file is selected. If, on the other hand, a new file is opened (without first closing the previous file) preferences will not be applied, but the local settings (changes made in the user interface) are applied for the new file as well.

In addition to the actual analysis options, there are various other editable options which have mainly influence on the usability of the software. Such options are e.g. the Range and Y-limit values of the data axis and various visualization options. The values of these options are preserved in memory and any changes made to them will be applied in the future sessions. Also the preference directories path from where the data file is searched for and in which the results are saved are preserved in memory. The last nine opened data files will also appear in the File menu of the user interface and can be reopened from



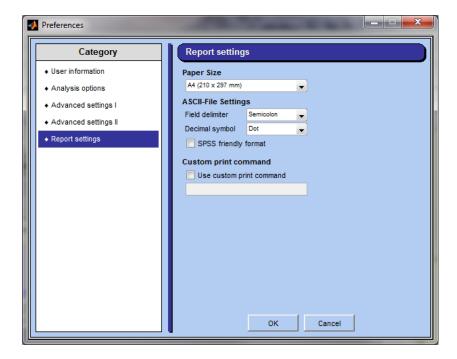


Figure 4.16: Set up preferences window of the software: Report settings category.

there.

All the preferences and preserved options used by Kubios HRV are saved in user specific folders¹.

Windows XP:

C:\Documents and Settings\<username>\Application Data\KubiosHRV

Windows Vista/Windows 7:

C:\Users\<username>\AppData\Roaming\KubiosHRV

Linux:

/home/<username>/.kubioshrv

where <username> is the name of your user profile. The folder will include three files: hrv_pref.dat, user_pref.dat, and HRVprefs.mat. The hrv_pref.dat file includes all the preferences for the analysis options, user_pref.dat includes the user information preferences, and HRVprefs.mat all the preferences related to the usability of the software. These files are created when the software is started for the first time and they will be updated whenever the preference values are edited. The original settings of the preferences can be restored by deleting these files.

¹Note that the Application Data folder in Windows XP and AppData folder in Windows Vista and 7 are hidden by default and are not visible in the Windows File Explorer if the "Show hidden files and folders" is not selected from the "Folder Options" section of the File Explorer.



Chapter 5

Sample run

In this chapter, we present a sample run of the software. The sample run is made for the GDF data file (gdf_ecg_data.gdf) distributed with this software. The sample data is measured from a healthy young male during an orthostatic test. The change in the posture is known to be reflected in the low frequency and high frequency HRV in an opposite way. That is, when subject stands up after lying for few minutes a strong decrease in the HF power and a more gradual increase in LF power are observed. In addition, a strong increase in heart rate is observed immediately after standing up, which aims to compensate the sudden decrease in blood pressure. In the sample run, this data file is analyzed by considering the lying and standing periods separately.

5.1 Sample run

In this sample run, we show how to make the time-domain, frequency-domain, and nonlinear analysis, for the lying and standing periods of the orthostatic measurement separately. This task can be easily accomplished in a single session. First, start the software and open the data file into the user interface. At this point, you can edit any of the analysis options to fit your demands. If you are about to analyze several data files with the same options, you better make these changes straight to the preferences.

The next thing to do is to select the RR interval samples to be analyzed. First, add a new sample to the RR interval axes because we want to analyze both the lying and standing periods. To do this, you can simply right click the RR axes, press Yes to the Add sample popup window, and OK to verify the sample properties. Now you will have two samples shown as yellow patches in the RR interval axes. Then change the sample ranges to cover the periods or interest as shown in Fig. 5.1. The easies way to change the samples' ranges is to edit them with the mouse as described in Section 4.2.2, but the ranges can also be changed by editing the Start and Length values in RR interval series options segment. Then check that the Sample analysis type option under the RR axis is set for Single samples. Then, analysis results are calculated for both samples separately. If, on the other hand, Merge samples is selected, then the two samples are first merged into one sample and the analysis results are calculated for this merged sample.

Since we are now only interested in the changes in LF and HF bands, we wish to remove the lowest frequency trend components from the RR series. These trend components affect on the time and frequency-domain variables and, thus, by removing the trend from the data enables these variables to better describe the LF and HF variability which we are interested of. We select to remove the trend with the smoothness priors based method. Once the detrending method is selected red lines appear over the RR interval data indicating the removed trend components. The smoothness of the removed trend in the smoothness priors method can be adjusted by changing the Lambda value. The smoothness priors detrending method can be compared to a high-pass filter in which the cutoff frequency is determined from the lambda value (bigger lambda corresponds to lower cutoff). The estimated cutoff frequency of the detreding method is also shown next to the Lambda value. Since we are now interested in LF and HF frequencies, we wish to make sure that the detrending does not remove those frequencies. This can be easily done by changing the Lambda value in such a way that the cutoff frequency is below 0.04 Hz. The effect of detrending can also be verified by inspecting how it changes the FFT spectrum. Here, we set the Lambda value to 500.

The time-domain, frequency-domain, and nonlinear analysis results for the selected samples can then be viewed in the results view segment. Just make sure that the results have been updated (check that

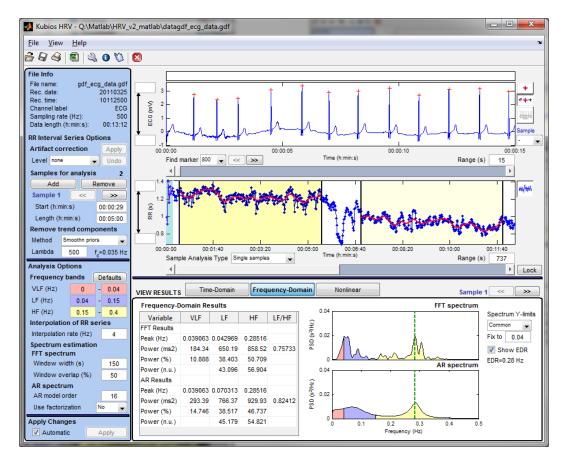


Figure 5.1: Sample run 1.

the Automatic is checked in Apply changes and if not press the Apply button). Press the Time-domain, Frequency-domain, or Nonlinear buttons to view the corresponding results. Note that the results are shown only for one of the samples at a time. To take a look at the results of the other sample press the \ll or \gg button on the top right corner of the results view segment (the text on the left changes to indicate which sample's results are shown, this sample will also be highlighted in the RR series axis). Note that you can force a common Y-limit for the spectra of both samples by setting a common Y-limit value manually in the frequency-domain results view. For example, we have here fixed the Y-limit value to $0.04~{\rm s}^2/{\rm Hz}$.

Once we are done with the analysis, we wish to save the analysis results in all possible formats. This can be done by selecting Save Results from the File menu or just by pressing the save button on the toolbar. Then select Save all (*.txt,*.mat,*.pdf) as the save type and enter a file name. You do not need to give any extension to the file name. The numeric results of the analysis will be saved in the *.txt text file, in the *.mat MATLAB file and the report sheets in the *.pdf file. The generated PDF-file will now include two pages, one for the results of the first RR interval sample (the lying period) and one for the second sample (standing period). These report sheet pages are shown in Figs. 5.2 and 5.3. In the text file, the results for the two samples are presented side by side as can be seen from Fig. 5.4. Note that you can also save the results in the "SPSS friendly" formatted text file if you select this option from the software preferences. If this option is selected the text file looks like the one shown in Fig. 5.5. That is all the parameter values are written in one row. The column headers indicate the corresponding parameter and the sample (_s1 indicates here the first sample, i.e. from the lying period). After the results for the first sample, you will find the same results for the second sample (_s2).

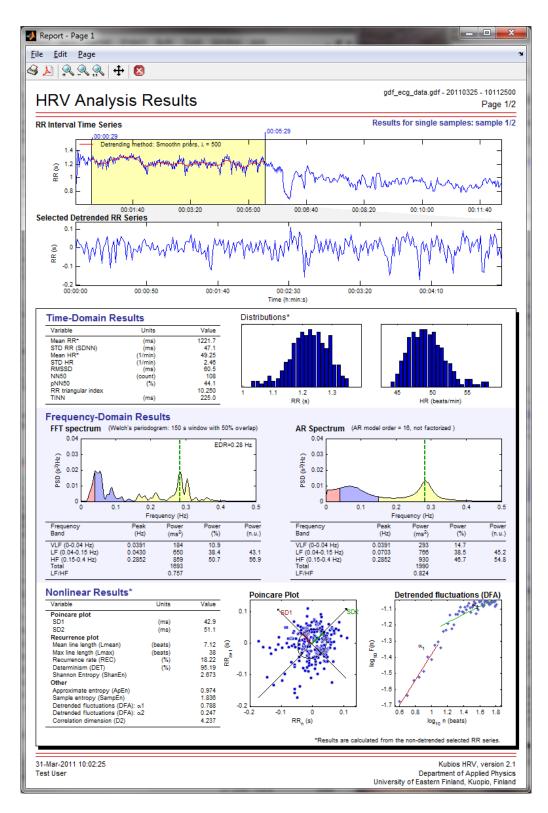


Figure 5.2: Sample run 1, results for the lying period of the orthostatic test.

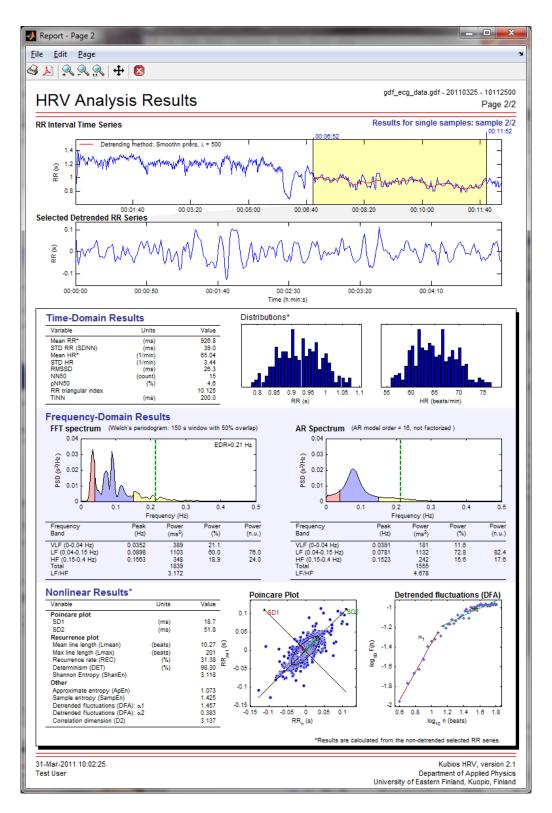


Figure 5.3: Sample run 1, results for the standing period of the orthostatic test.

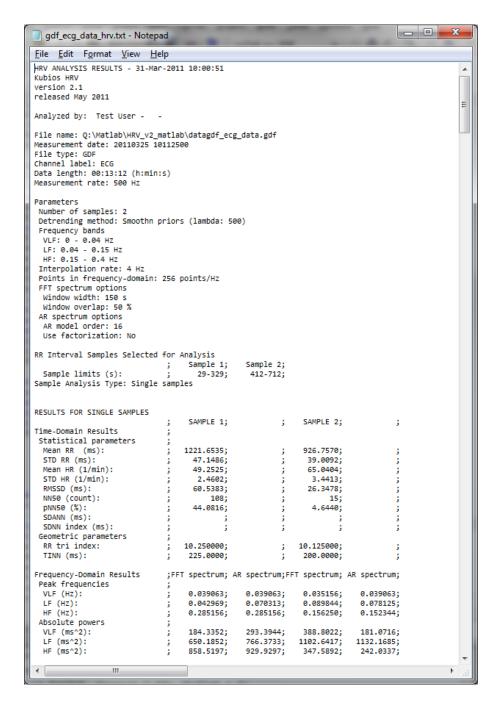


Figure 5.4: Sample run 1, results saved in an ASCII file.

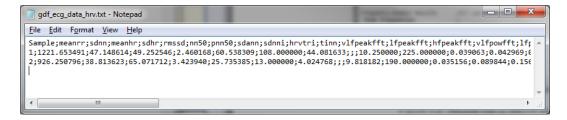


Figure 5.5: Sample run 1, results saved in an SPSS friendly ASCII file.



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